

Newton's Method for PDE II

Ryan McPeck

Northern Arizona University

April 13, 2010

Outline

A Quick Review

Newton's Method

- Standard Form

- Newton's Method in Higher Dimensions

- A Useful Theorem

Overview of Programming and Results

- Programming

- Modifying Newton's Method Further

- Results

Acknowledgments

General Information

- ▶ A partial differential equation, or PDE, is a differential equation involving partial derivatives.
- ▶ PDEs have many applications:
 - ▶ Harvesting
 - ▶ Starburst
 - ▶ Heat
 - ▶ Waves
- ▶ Specifically we studied $\Delta u + su + u^3 = 0$ on the unit disk centered at the origin in \mathbb{R}^2 with $u = 0$ on the boundaries.

Standard Form

$$\blacktriangleright x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$$

Newton's Method in Higher Dimensions

- ▶ $f : \mathbb{R}^m \rightarrow \mathbb{R}^m$ an arbitrary function
- ▶ $a_{k+1} = a_k - (J_f(a_k))^{-1}f(a_k)$
 - ▶ J_f is a Jacobian of the function f , or a vector of first derivatives

Theorem

- ▶ Let $J : X \rightarrow \mathbb{R}$ (Recall that X is the function space that we are working in)
- ▶ $\nabla J(u) = 0 \iff u$ is a solution to the pde
- ▶ $J(u) = \int \frac{|\nabla J(u)|^2}{2} - F(u) d\hat{x}$
 - ▶ $F(u) = \frac{su^2}{2} + \frac{u^4}{4} = \int_0^u f(s) ds$

Proof in One Direction

- ▶ Suppose $u(x)$ is a solution to $u'' + u^3 = 0$. Then $\int (u'' + u^3)v \, dx = 0$ for all v .
- ▶ $J(u) = \int \frac{|\nabla J(u)|^2}{2} - \frac{u^4}{4} \, d\hat{x}$
- ▶ $J'(u)(v) = \int u'v' - u^3v = -\int (u'' + u^3)v = -\langle u'' + u^3, v \rangle$
- ▶ By definition, $\nabla J(u) = -(u'' + u^3) = 0$.

Programming

- ▶ Language: MATLAB
- ▶ Goals:

- ▶ Find roots of $J(u) = \int \frac{|\nabla J(u)|^2}{2} - F(u) d\hat{x}$ using Newton's Method
- ▶ Display and interpret results

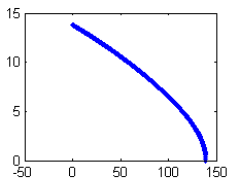
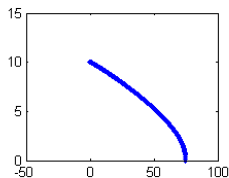
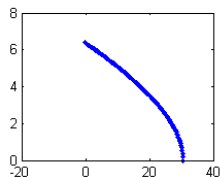
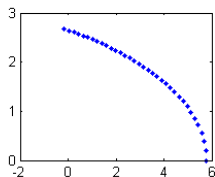
Gradient Newton Galerkin Algorithm

- ▶ Mentor and colleagues have successfully used modified Newton's Method to find solutions for PDE
- ▶ Our particular PDE of interest was studied by a student working on his master's thesis
- ▶ $a^{k+1} = a^k - \left(\frac{\partial g_i}{\partial a_j}\right)^{-1} g(a^k)$
 - ▶ $\frac{\partial g_i}{\partial a_j}$ is the Hessian, a matrix filled with second derivatives
 - ▶ g is the gradient that we are trying to find roots of

Filling in the Gradient and the Hessian

- ▶ $g_i = J'(u)(\Psi_i) = a_i \lambda_i - \int f(u) \Psi_i$
- ▶ $h_{ij} = J''(u)(\Psi_i, \Psi_j) = \lambda_i \delta_{ij} - \int f'(u) \Psi_i \Psi_j$
- ▶ Integrals were computed numerically with Riemann sums
- ▶ Solve: $\frac{\partial g_i}{\partial a_j} \cdot \chi = g$ to avoid calculating the inverse of the Hessian
- ▶ Tolerances and iteration limits imposed to find and save off solutions

Bifurcation Diagrams



What These Solutions Look Like

- ▶ Solutions can be reassembled using linear combinations
- ▶ Sadly, we have not quite figured out the easiest way to do this yet
- ▶ Recall graphics from last presentation

Acknowledgments

- ▶ Dr. John Neuberger, mentor
- ▶ Mr. Jeff Rushall, for all the opportunities to practice presenting
- ▶ NAU NASA Space Grant program
- ▶ University of Arizona and conference organizers